INFLUENCE OF SEGMENTATION ON THE PRECISION OF CIRCUIT BASED METHODS

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A b s t r a c t: Numerical methods are based on segmenting the domain of calculations. In this paper the influence of wire segmentation on the precision of calculations of approximate numerical models for analysis of grounding systems is investigated. It is well known that increasing the number of segments leads to increased precision in the calculations. However, the maximum number of segments is limited by the conditions from the thin wire approximation that is implemented by these methods. As a result convergence of the numerical technique may not always be reached. In this paper convergence of the relative error obtained by each numerical method as a function of relative segment length is parametrically investigated.

Key words: segmentation; numerical models; convergence

INTRODUCTION

Numerical methods are based on segmenting the domain of calculations. In the field of grounding system analysis there is a plethora of widely used exact and approximate numerical methods. The most important approximate methods are based on representing each segment of the conductor by an equivalent circuit branch. Most circuit models implement approximate solutions of the so called Mixed Potential Integral Equation (MPIE), while the rigorous Electromagnetic Model (EM) [1] yields the most precise results by numerically solving the MPIE with fewest approximations. The EM implements numerical solution of the MPIE by the Method of Moments (MoM) [2]. In the scientific public it is recognized as a reference method in the field.
CIRCUIT BASED MODELS

The most important approximate methods are based on creating equivalent circuit branches to represent each segment of the conductor. The electrode is divided into fictitious segments whose length \( \Delta l \) has to be much larger that its radius \( a \) (\( \Delta l > 10a \) is usually adequate) in order to maintain the conditions for the thin wire approximation.

A) Lumped circuit model

The basic principle of the lumped circuit \((R-L-C)\) model is to represent the conductor as a whole by a circuit derived from its input impedance. According to [3] the high-frequency model for the impedance is an inductor \( L \) in a series with a parallel combination of a capacitor \( C \) and a resistor \( R \). At low frequencies this model reduces to the static ground resistance of the conductor \( R \). The parameters describe the conductor as a single segment and therefore do not include the inductive, capacitive or conductive coupling between different parts of the conductor.

The values of the circuit elements for a vertical grounding rod with radius \( a \) and length \( \Lambda \) \((\Lambda >>a)\), from [4].

\[
R_s = \frac{\rho}{2\pi a} \left(\log \frac{4a}{\Delta l} - 1\right) \text{ (\(\Omega\)),}
\]

\[
L_s = \frac{\mu_0 a}{2\pi} \left(\log \frac{4a}{\Delta l} - 1\right) \text{ (H),}
\]

where \( \rho \) is the specific resistivity of earth. The values of the circuit elements [3, 5] in the case of a horizontal grounding electrode buried in homogeneous earth at depth \( d \) \((\Lambda >>a, \Lambda >>d)\) are:

\[
R_s = \frac{\rho}{\pi a} \left(\log \frac{2a}{\sqrt{\pi ad}} - 1\right) \text{ (\(\Omega\)),}
\]

\[
L_s = \frac{\mu_0 a}{\pi} \left(\log \frac{2a}{\sqrt{\pi ad}} - 1\right) \text{ (H).}
\]

The value of the capacitor is calculated by

\[
C_{v,h} = \frac{\rho e}{R_{v,h}} \text{ (F).}
\]

An evolved (and widely used [6 – 8]) version of the \(R-L-C\) model is presented in Figure 1. Basically, it is a discrete approximation of a transmission line (TL) with parameters per length obtained from (1) – (3).

![Fig. 1. R-L-C circuit representation of a segmented conductor](image)

B) Circuit based models that include electromagnetic coupling

1. Circuit based method – CBM

One of the most significant circuit based methods – CBM, was introduced in 1998 [9]. It is frequently used for analysis of grounding systems [10], [11], [12], [13] and [14]. Electromagnetic influence between segments is taken into account, but propagation effects on the EM fields are not considered in CBM.

The longitudinal impedance of each segment of a perfectly conducting wire is of inductive character expressed in CBM as

\[
L_{mm} = \int_{S_m} \bar{t}_m \cdot \bar{t}_n \psi_A(l, l; m, n) dl,
\]

where \( \Delta l_m \) is the length of the \( m \)-th segment, \( t_m \) and \( t_n \) are unit vectors parallel to the observed- and source segment, respectively.

The transversal impedances of each segment, $Z_{mn}^{t}$, are derived via the influence of the leakage current exiting segment $n$, on segment $m$,

$$Z_{mn}^{t} = \frac{1}{j\omega} \frac{1}{\Delta l_n} \int_{\Delta l_n} \tilde{I}_m \cdot \tilde{I}_n (l_n, l_m) dl,$$  (7)

where $\Delta l_n$ is the length of the $n$-th (source) segment. The elements defined by (6) and (7) constitute an equivalent circuit branch that represents each segment of the conductor. The resulting circuit is solved via conventional nodal analysis to obtain the potentials of the nodes.

The form of $\psi_A$ and $\psi_V$ in (6) and (7) equals

$$\psi_A(l_{n1}, l_{n2}; m) = \int_{l_{n1}}^{l_{n2}} G_A(n, m) dl,$$  

$$\psi_V(l_{n1}, l_{n2}; m) = \int_{l_{n1}}^{l_{n2}} G_V(n, m) dl,$$  (8)

where $G_A$ and $G_V$ are magnetic vector potential and electric scalar potential Green’s functions for an unbounded medium:

$$G_A(\mathbf{r}', \mathbf{r}) = \frac{\mu_0}{4\pi} \frac{\exp(-j\kappa_1|\mathbf{r}' - \mathbf{r}|)}{|\mathbf{r}' - \mathbf{r}|},$$

$$G_V(\mathbf{r}', \mathbf{r}) = \frac{1}{4\pi\varepsilon} \frac{\exp(-j\kappa_1|\mathbf{r}' - \mathbf{r}|)}{|\mathbf{r}' - \mathbf{r}|},$$  (9)

where $\varepsilon = \varepsilon + j\sigma/\omega$ is the complex permittivity of the medium and $\sigma = 1/\rho$.

The way to solving integrals in (6) and (7) within CBM is limited by the quasi-stationary approximation, i.e. only the first element of the Maclaurin series of $G_{A,V}$ is taken into account. All remaining elements of (9) are neglected, yielding

$$G_A(\mathbf{r}', \mathbf{r}) = \frac{\mu_0}{4\pi|\mathbf{r}' - \mathbf{r}|},$$

$$G_V(\mathbf{r}', \mathbf{r}) = \frac{1}{4\pi\varepsilon|\mathbf{r}' - \mathbf{r}|}.$$  (10)

Substituting (10) in (6) and (7) yields the same type of double integrals that have analytical solution for the usually implemented combinations of grounding conductors.

Traditional and modified image methods [15, 16] are implemented with CBM to take into account the influence of earth/air interface on the form of Green’s functions.

2. Hybrid electromagnetic model – HEM

The hybrid electromagnetic model [17] is a dual approach in analysis of grounding systems – it combines numerical electromagnetic calculations with electric circuit theory. The hybrid electromagnetic model (HEM) is frequently used for analysis of grounding systems due to its precision [12–14] and [17–22].

Within HEM, the longitudinal and transversal impedances of an arbitrary segment $m$ are defined by (6) and (7), respectively.

Unlike the quasi-static forms in CBM, the Green’s functions in the above mentioned expressions maintain the full-wave form. In this paper the following technique from [23] is implemented to approximate (8):

$$\text{Exp}(-j\kappa_1 r_{mn}) \int_{\Delta l_n} \int_{\Delta l_m} \frac{1}{|\mathbf{r}' - \mathbf{r}|} dl'd,$$  (11)

where $r_{mn}$ is the distance between middle points of the source and segment of interest.

Up-to-date, authors have implemented the HEM method using the traditional and modified image methods [15, 16], as well as complex images [22], to take into account the presence of earth/air interface.

RESULTS

In this section, convergence of numerical calculations as a function of relative segment length is parametrically investigated. The segment length ratio – S.L.R, is calculated as a ratio of segment length vs. the length of the whole conductor. Thus, S.L.R. is inversely proportional to the number of segments, $N$:

$$\text{S.L.R.} = 100 \cdot \frac{\Delta l}{A} (\%) \quad (= 1/N)$$  (12)

The horizontal grounding electrode, as one of the most frequently used types of grounding electrical systems is analyzed, presented in Figure 2.
The relative error in the impedance magnitude for the horizontal conductor is calculated by

$$\Delta = \left| \frac{|Z| - |Z^{REF}|}{|Z^{REF}|} \right| \times 100 \, \%,$$

(13)

where $Z$ is the magnitude of the impedance to ground calculated by implementation of HEM, CBM and the discrete $R$-$L$-$C$ model, and $Z^{REF}$ is calculated by the rigorous EM method.

Tables 1, 2 and 3 present the value of S.L.R. at which the error converges in the calculations for a horizontal grounding conductor with length 4, 10 and 40 m, respectively, for several values of $\rho$ and $f$.

It is visible from Tables 1, 2 and 3 that, in general, for high frequencies lower number of segments is sufficient to reach convergence in the calculations.

**Table 1**

<table>
<thead>
<tr>
<th>Frequency (Hz)</th>
<th>$\rho = 50 , \Omega m$</th>
<th>$\rho = 100 , \Omega m$</th>
<th>$\rho = 500 , \Omega m$</th>
</tr>
</thead>
<tbody>
<tr>
<td>10$^3$</td>
<td>CBM 12</td>
<td>CBM 13</td>
<td>CBM 11</td>
</tr>
<tr>
<td>10$^6$</td>
<td>CBM 25</td>
<td>CBM 35</td>
<td>CBM 10</td>
</tr>
<tr>
<td>5-10$^6$</td>
<td>CBM 17</td>
<td>CBM 35</td>
<td>CBM 9</td>
</tr>
</tbody>
</table>

**Table 2**

<table>
<thead>
<tr>
<th>Frequency (Hz)</th>
<th>$\rho = 50 , \Omega m$</th>
<th>$\rho = 100 , \Omega m$</th>
<th>$\rho = 500 , \Omega m$</th>
</tr>
</thead>
<tbody>
<tr>
<td>10$^3$</td>
<td>CBM 6</td>
<td>CBM 7</td>
<td>CBM 5</td>
</tr>
<tr>
<td>10$^6$</td>
<td>CBM 11</td>
<td>CBM 17</td>
<td>CBM 35</td>
</tr>
<tr>
<td>5-10$^6$</td>
<td>CBM 25</td>
<td>CBM 35</td>
<td>CBM 16</td>
</tr>
</tbody>
</table>

**Table 3**

<table>
<thead>
<tr>
<th>Frequency (Hz)</th>
<th>40 m long conductor</th>
</tr>
</thead>
<tbody>
<tr>
<td>$\rho = 50 , \Omega m$</td>
<td>$\rho = 100 , \Omega m$</td>
</tr>
<tr>
<td>10$^3$</td>
<td>CBM 5</td>
</tr>
<tr>
<td>10$^6$</td>
<td>CBM 9</td>
</tr>
<tr>
<td>5-10$^6$</td>
<td>CBM 9</td>
</tr>
</tbody>
</table>

Figures 3, 4 and 5 show the relative error in the magnitude of the impedance to ground for earth with specific resistivity: $\rho = 50 \, \Omega m$, $\rho = 100 \, \Omega m$ and $\rho = 500 \, \Omega m$, respectively, as a function of S.L.R. (segment length ratio). The error is calculated by implementation of HEM, CBM, and the discrete $R$-$L$-$C$ method on a) 4 m, b) 10 m and c) 40 m long horizontal grounding conductor, controlled by results obtained using the rigorous EM method [1]. The analyzed frequency in the presented cases is 1 kHz. The relative error in the impedance magnitude at a frequency of 1 MHz (which is considered high in the analysis of grounding conductors) obtained as a function of S.L.R. is presented in Figures 6, 7 and 8, for earth with specific resistivity: $\rho = 50 \, \Omega m$, $\rho = 100 \, \Omega m$ and $\rho = 500 \, \Omega m$, respectively. The relative error in the impedance magnitude at a frequency of 5 MHz (which is considered very high in the analysis of grounding conductors) obtained as a function of S.L.R. is presented in Figures 9, 10 and 11, for specific resistivity of earth: $\rho = 50 \, \Omega m$, $\rho = 100 \, \Omega m$ and $\rho = 500 \, \Omega m$, respectively.

**DISCUSSION**

It is evident from Figures 3, 4 and 5 that for low frequencies (1 kHz) the segmented $R$-$L$-$C$ model converges at large values of S.L.R. (small number of segments). At higher frequencies (1 MHz and 5 MHz, presented on Figures 6–11) this model yields extremely high relative error and does not converge for a sensible value of S.L.R. Because of this fact, it is not included in Tables 1, 2 and 3.

Regarding methods CBM and HEM, the relative error in the impedance magnitude at low frequency (1 kHz) converges at S.L.R. $\approx 10$ (Figures 3, 4 and 5). In this case larger number of segments is required to reach convergence in the calculations.

It may be observed that at high frequencies (Figures 6–11) the convergence value of S.L.R. depends strongly on the value of $\rho$ for each investigated method.
Fig. 3. Relative error in the impedance magnitude at 1 kHz, $\rho = 50 \, \Omega \text{m}$

Fig. 4. Relative error in the impedance magnitude at 1 kHz, $\rho = 100 \, \Omega \text{m}$
Fig. 5. Relative error in the impedance magnitude at 1 kHz, $\rho = 500 \, \Omega m$

Fig. 6. Relative error in the impedance magnitude at 1 MHz, $\rho = 50 \, \Omega m$
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Fig. 7. Relative error in the impedance magnitude at 1 MHz, $\rho = 100 \, \Omega \text{m}$

Fig. 8. Relative error in the impedance magnitude at 1 MHz, $\rho = 500 \, \Omega \text{m}$

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Fig. 9. Relative error in the impedance magnitude at 5 MHz, $\rho = 50 \, \Omega m$

Fig. 10. Relative error in the impedance magnitude at 5 MHz, $\rho = 100 \, \Omega m$
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REFERENCES


Fig. 11. Relative error in the impedance magnitude at 5 MHz, \( \rho = 500 \, \Omega \text{m} \)


